SONCEBOZ

▶ Mechatronic systems

8660-15 C

Stepper motor with integrated driver

RoHS compliant 2002/95/EC

- **Low noise**
- **cool running ..... 1/8 & 1/256 step**
- **Dimensions ..... 57.2 x 57.2 x 55.85 mm**
- **Interface ..... Pulse / Direction / Boost / Enable / Stepselect**

SMART LOW NOISE ACCURACY

The smart actuator is a complete drive system with electronic, able to detect position and / or can be interfaced via a communication bus.

▶Main Features

• Compact
A small size and a very low temperature rise are obtained through the integration of a driver in the hybrid bipolar stepper motor.

• High frequency interface
The driver allows a high input frequency up to 200 kHz. All inputs have opto-couplers.

• Low noise
Thanks to the high resolution of 256 microsteps per step and the driver optimization, the motor rotates with practi- cally no noise and vibration.

• Very low temperature rise
The temperature rise is typically 15° C when the motor operates continuously for 2 hours at nominal current (value obtained with the motor screwed on a 150 x 150 x 6 mm aluminium plate). In the same operating conditions, the temperature rise is typically 25° C at boost current.

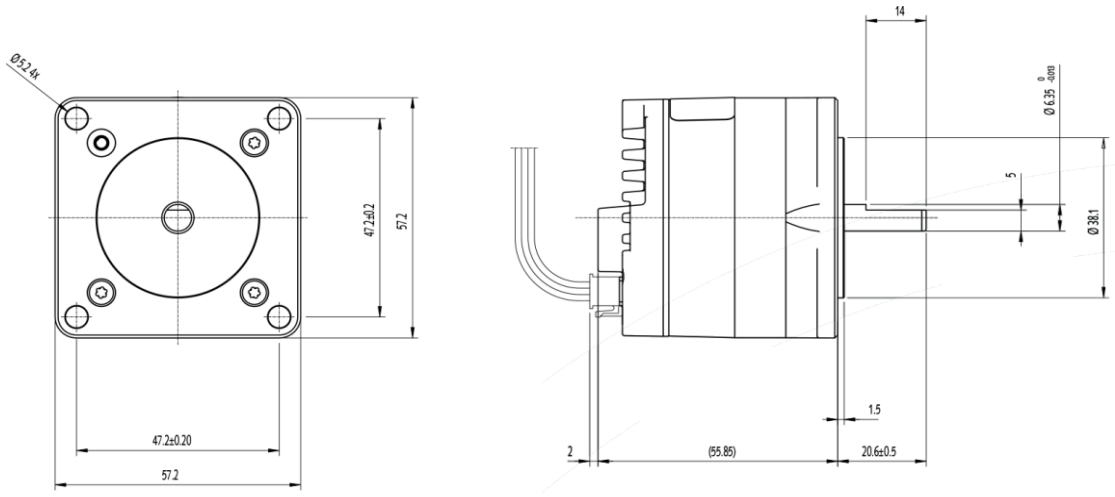
• Intelligent driver
The boost option is particularly useful when a higher torque is required (for example during acceleration / deceleration ramps). The current is automatically reduced to 2/3 of the nominal value at standstill. This feature minimizes the temperature rise.

▶Technical data

Power supply (+/- 20%)	**24 VDC**
Maximal input power (Full load, Iboost ON)	**38 W**
Maximum input frequency	**200 kHz**
Rotor inertia	**131 gcm^2**
Detent torque	**26 mNm**
Holding torque at standstill (reduced current)	**200 mNm**
Maximum torque at low speed	**325 mNm**
Weight	**392 g**
Microsteps per revolution	**1600/51200**

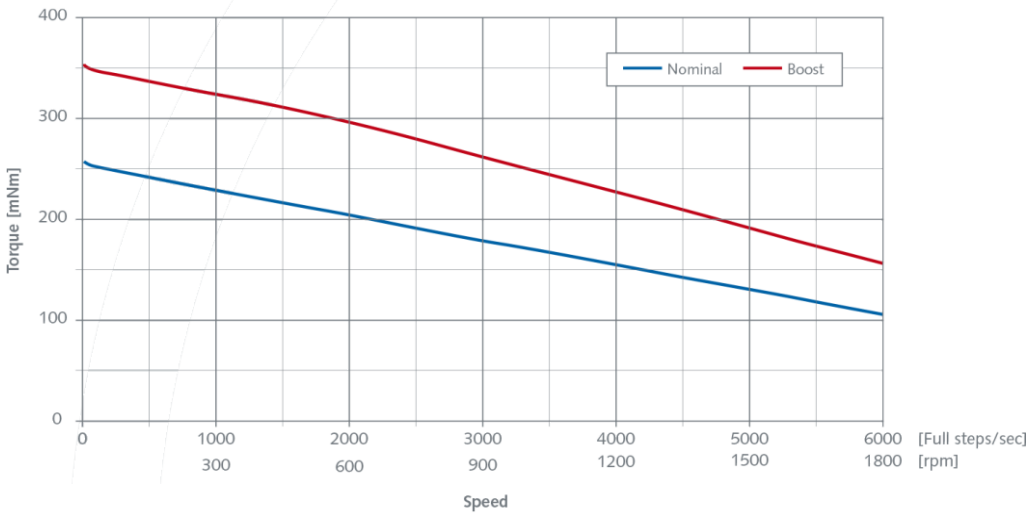
▶Dimensions

Drawing not to scale. All dimensions in mm.

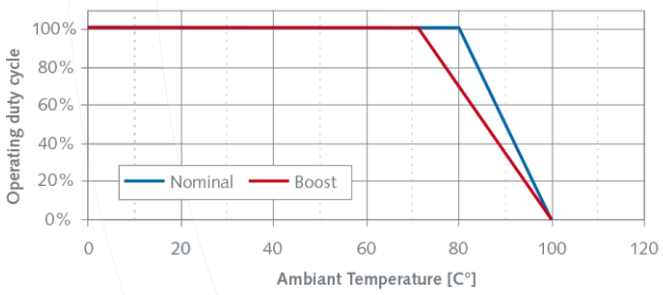


▶Thermal and torque characteristics

• Dynamic torque



• Max duty cycle vs temperature range



Values obtained with the motor screwed on an aluminum plate (dimensions 150 x 150 x 6 mm)

▶Electrical Interface

CONNECTOR

- Header MICRO-FIT 3.0 8p
- MOLEX n° 43045 0812

Front view

Matching products:
Molex female terminal: 43030 (series)
Molex female housing: 43025 0800

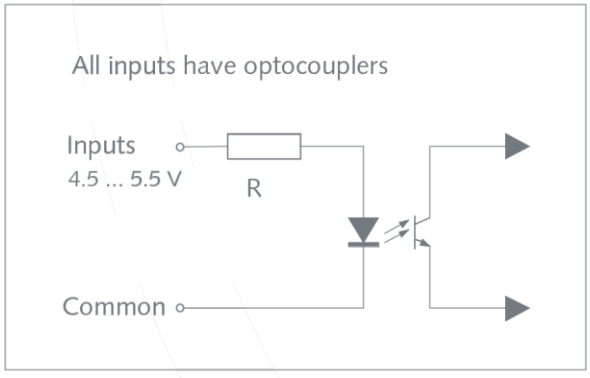
PIN ASSIGNMENTS

+24 VDC ..... Power supply
GND ..... Power ground
Common ..... Ground for logical inputs (Step select, Dir, Enable, Boost, Pulse)
Pulse ..... Microstep clock input (active on rising edge)

Pin	Description	State 0	State 1
Step select	Microstep resolution	1/8 step (= 1600 microsteps/revolution)	1/256 step (=51200 microsteps/revolution)
Dir	Direction of rotation	CW	CCW
Enable	Power ON	OFF	ON
Boost	Increase in torque	OFF	ON

Note: Step select input is only selectable when Enable = 0 (current OFF)

INPUTS



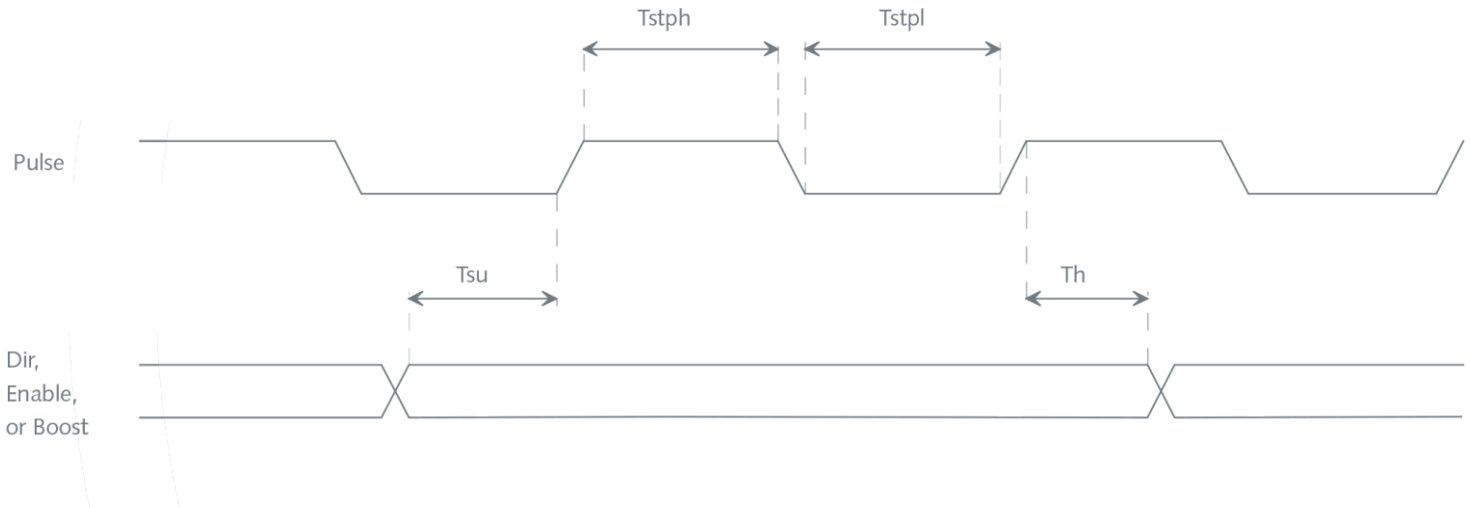
R = 470 Ω, excepted for the pulse input R = 220 Ω.

An external resistor can be added in series with the input to increase the logical voltage up to 24 VDC. For Vin = 24 VDC, the external resistors would be 1.2 kΩ for the pulse and 2.7 kΩ for the others inputs.

CHARACTERISTICS

Characteristics	Symbol	Min	Typ	Max	Unit
Input control voltage low	Vil	0	0	0.8	V
Input control voltage high	Vih	4.5	5	5.5	V
Input current high [Pulse]	Lin	12	16	20	mA
Input current high [Dir, enable, Boost]	Lin	6.5	8	9.5	mA
STEP pin low	Tstpl	2.5	-	-	µs
STEP pin high	Tstph	2.5	-	-	µs
Setup time for input change to STeP	Tsu	900	-	-	µs
Hold time for input change from STeP	Th	2.5	-	-	µs

TIMING DIAGRAM



►Working conditions

• **Operating temperature range** ..... 0 to 80° C
(Inominal, see graph. Max duty)

• **Protection class** IP50

• **Thermal and over/under voltage protections**

If the motor temperature exceeds 100° C or if the supply voltage comes outside its operating range, the driver is automatically switched off. This is intended to protect components from failure due to excessive temperature or under / over voltage.

To restart the motor after cut off, a rising edge must be applied on the ENABLE input when temperature or voltage error has been cleared. Thermal hysteresis is ~10° C and voltage hysteresis is ~1 V.

►Installation

• **Cables and power supply:**

The cables used must have an insulation temperature of at least 105° C. The motor interface must be SELV type (Sepa- rated Extra Low Voltage). The cables between the power supply and motor must no be longer than 1 m and a minimal AWG24 diameter must be respected. Every system is delivered with 2 fastening screws and a 25 cm connection cable.

• **Temperature and protections:**

Max. temperature of motor and electronic ..... 100° C

It is possible to improve the motor's heat dissipation by fixing it to a metal plate which acts as a heat sink and by using thermoconductive paste. If the motor is accessible or its temperature is high, it may be necessary to fit protecting elements for the safety of the user.

►Options and adaptations

• Options (minimum quantity required):

- Inputs 24 VDC
- Inputs configuration on request
- Choice of 2 resolutions in the range from full step (1/1) to 1/256 step

• Following adaptations available on request:

- Communications bus (CAN, RS485, …)
- Programmable positioning sequences
- Stand-alone operation
- PC programmable
- Mechanical adaptation, connections, etc.

►Ordering information

Type	Specific characteristic	Ordering code
8660-15 Low noise cool running	1/8 & 1/256 step, low temperature rise	8660R908