



## ► Mechatronic systems

**8656-18**

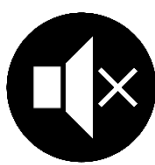
### Stepper motor with integrated driver



- **Standard version..... 1/2 & 1/8 step**
- **Low noise version... 1/8 & 1/256 step**
- **Dimensions ..... 43.3x53.5x65.8 mm**
- **Interface ..... Pulse / Direction / Boost / Enable / Stepselect**



SMART



LOW NOISE



ACCURACY

This complete drive system is composed of a reliable stepper motor with an integrated driver assembled in a compact housing.

### ► Main Features

- **Compact**  
An excellent size / torque ratio is obtained through the integration of a driver in the hybrid bipolar stepper motor.
- **High frequency interface**  
The driver allows a high input frequency up to 200 kHz. All inputs have opto-couplers.
- **Low noise**  
Thanks to the high resolution of 256 microsteps per step and the driver optimization, the motor rotates with practically no noise and vibration (low noise version).
- **Intelligent driver**  
The boost option is particularly useful when a high torque is required (during acceleration / deceleration ramps). The current is automatically reduced to 2/3 of the nominal value at standstill. This feature minimizes the temperature rise.

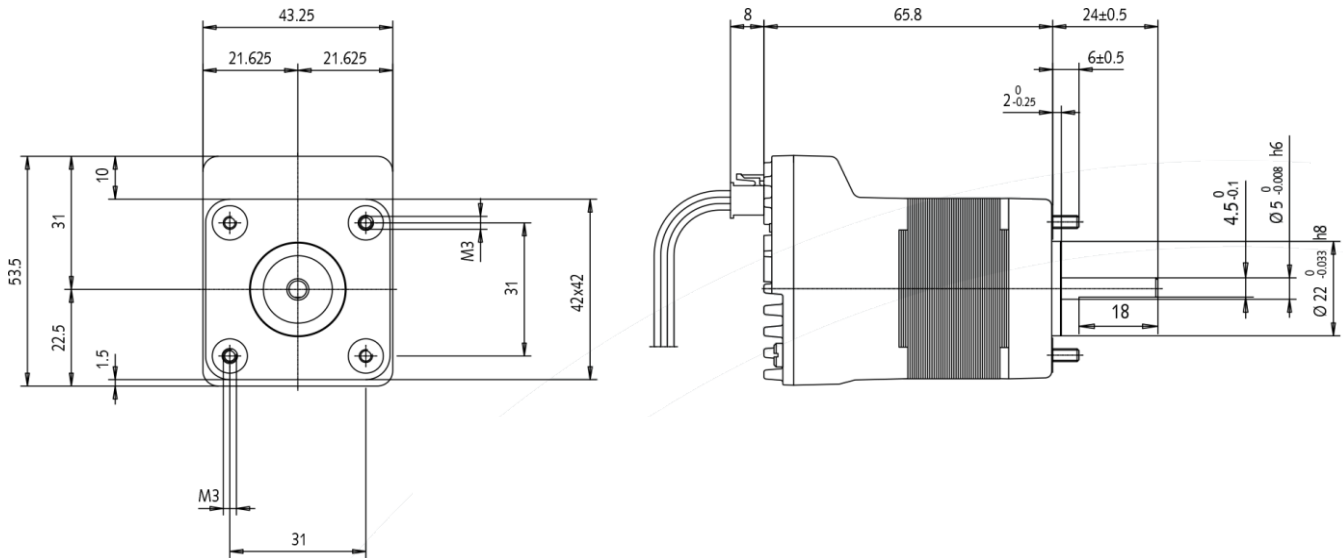
### ► Technical data

Power supply (+/- 20%)	24 VDC
Maximal input power (Full load, Iboost ON)	39 W
Maximum input frequency	200 kHz
Rotor inertia	35 gcm <sup>2</sup>
Detent torque	13 mNm
Holding torque at standstill (reduced current)	200 mNm
Maximum torque at low speed	300 mNm
Weight	367 g

Type	Mirosteps per revolution
Standard	400 / 1600
Low noise	1600 / 51200

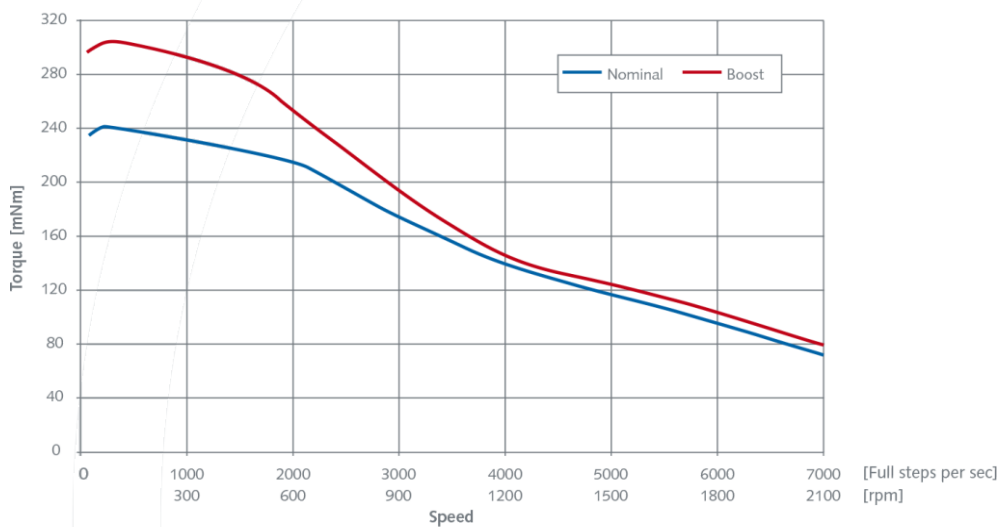
## ► Dimensions

Drawing not to scale. All dimensions in mm.

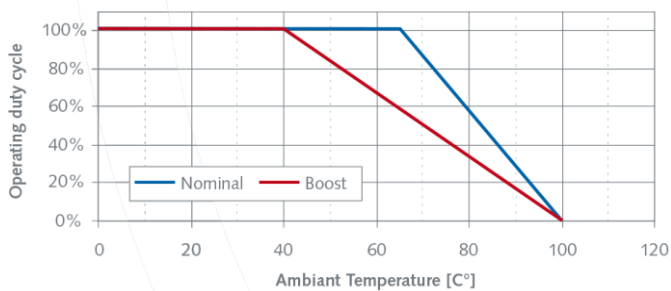


## ► Thermal and torque characteristics

### • Dynamic torque



### • Max duty cycle vs temperature range



Values obtained with the motor screwed on an aluminum plate (dimensions 150 x 150 x 6 mm)

## ► Electrical Interface

### CONNECTOR

• Header MICRO-FIT 3.0 8p

• MOLEX n° 43045 0812



#### Matching products:

Molex female terminal: 43030 (series)

Molex female housing: 43025 0800

Front view

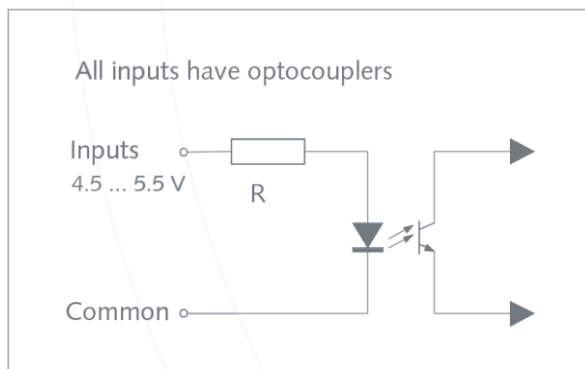
### PIN ASSIGNMENTS

+24 VDC .....	Power supply
GND .....	Power ground
Common .....	Ground for logical inputs (Step select, Dir, Enable, Boost, Pulse)
Pulse .....	Microstep clock input (active on rising edge)

Pin	Description	Version	State 0	State 1
Step select	Microstep resolution	Standard version	1/2 step (= 400 microsteps/revolution)	1/8 step (=1600 microsteps/revolution)
		Low noise version	1/8 step (= 1600 microsteps/revolution)	1/256 step (=51200 microsteps/revolution)
Dir	Direction of rotation	All	CW	CCW
Enable	Power ON	All	OFF	ON
Boost	Increase in torque	All	OFF	ON

Note: Step select input is only selectable when Enable = 0 (current OFF)

### INPUTS



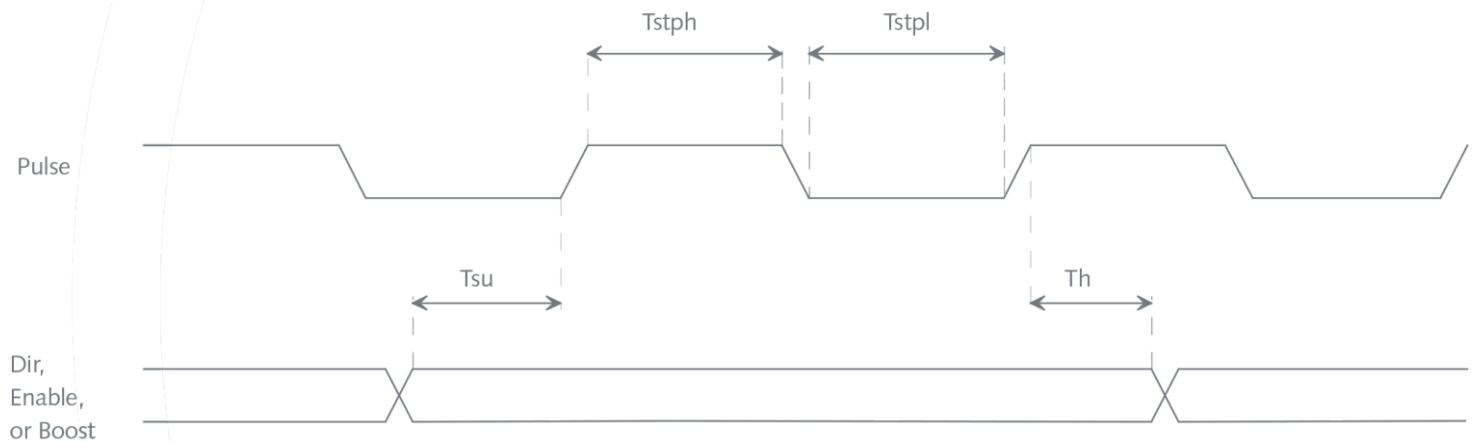
$R = 470 \, \Omega$ , excepted for the pulse input  $R = 220 \, \Omega$ .

An external resistor can be added in series with the input to increase the logical voltage up to 24 VdC. For  $V_{in} = 24 \, \text{VdC}$ , the external resistors would be 1.2 k $\Omega$  for the pulse and 2.7 k $\Omega$  for the others inputs.

## CHARACTERISTICS

Characteristics	Symbol	Min	Typ	Max	Unit
Input control voltage low	Vil	0	0	0.8	V
Input control voltage high	Vih	4.5	5	5.5	V
Input current high [Pulse]	Lin	12	16	20	mA
Input current high [Dir, enable, Boost]	Lin	6.5	8	9.5	mA
STEP pin low	Tstpl	2.5	-	-	μs
STEP pin high	Tstph	2.5	-	-	μs
Setup time for input change to STeP	Tsu	800	-	-	μs
Hold time for input change from STeP	Th	2.5	-	-	μs

## TIMING DIAGRAM



## ► Working conditions

- **Operating temperature range** ..... 0 to 65° C  
(Inominal, see graph. Max duty)
- **Protection class** ..... IP50
- **Thermal and over/under voltage protections**

If the motor temperature exceeds 100° C or if the supply voltage comes outside its operating range, the driver is auto-matically switched off. This is intended to protect components from failure due to excessive temperature or under / over voltage.

To restart the motor after cut off, a rising edge must be applied on the ENABLE input when temperature or voltage error has been cleared. Thermal hysteresis is ~10° C and voltage hysteresis is ~1 V.

## ► Installation

- **Cables and power supply:**

The cables used must have an insulation temperature of at least 105° C. The motor interface must be SELV type (Sepa- rated Extra Low Voltage). The cables between the power supply and motor must no be longer than 1 m and a minimal AWG24 diameter must be respected. Every system is delivered with 2 fastening screws and a 25 cm connection cable.

- **Temperature and protections:**

Max. temperature of motor and electronic ..... 100° C

It is possible to improve the motor's heat dissipation by fixing it to a metal plate which acts as a heat sink and by using thermoconductive paste. If the motor is accessible or its temperature is high, it may be necessary to fit protecting elements for the safety of the user.

## ► Options and adaptations

### • Options (minimum quantity required):

- Inputs 24 VDC
- Inputs configuration on request
- Choice of 2 resolutions in the range from full step (1/1) to 1/256 step

### • Following adaptations available on request:

- Communications bus (CAN, RS485, ...)
- Programmable positioning sequences
- Stand-alone operation
- PC programmable
- Mechanical adaptation, connections, etc.

## ► Ordering information

Type	Specific characteristic	Ordering code
8656-18 Low noise	1/8 & 1/256 step	8656R931
8656-18 Standard	1/2 & 1/8 step	8656R930